

Damage Tolerance and Durability of Adhesively Bonded Composite Structures

04-C-AM-PU

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CT Sun (PU-AERO)

Administrative Outline

- Pls:
 - Thomas Siegmund (PU-ME)
 - CT Sun (PU-AERO)
- Technical Monitor: Curt Davies
- Cost share: Purdue University
- Additional Funding: Caterpillar Inc.

Research Outline: past years (also H. Kim)

- **Characterization of Adhesive Joints**
 - **Toughness**
 - **Strength**
 - **Environmental degradation**
 - **Bondline thickness**
 - **Size effects in joints**
- **Training**
 - **Computational Fracture Mechanics course
(online offering in planning for Spring 09)**

Research Outline 2009

- Project #1 (Siegmond):
 - **Numerical Simulation of Fatigue Crack Growth: Cohesive Zone Models vs. XFEM**
- Project #2 (Sun):
 - **Development of Improved Hybrid Joints**

Numerical Simulation of Fatigue Crack Growth: Cohesive Zone Models vs. XFEM

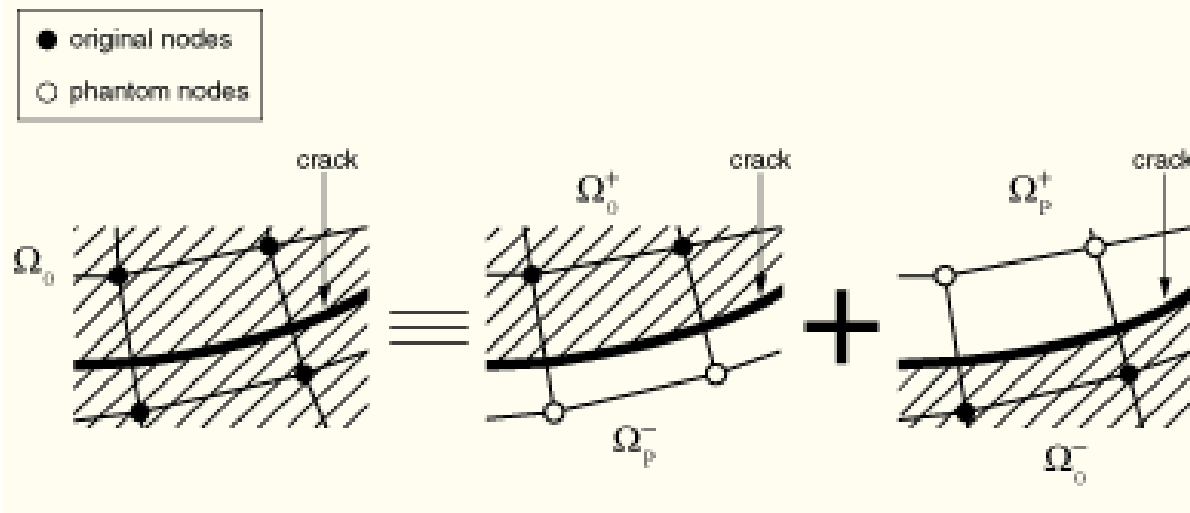
Thomas Siegmund
Purdue University

Research Accomplishments

- Tools for “Certification by Simulation”
 - Crack initiation and growth at arbitrary site and path (**adhesive**)
 - Compare cohesive zone model approach to XFEM
 - Implement fatigue crack growth in XFEM
 - Scenario: Failure from
 - Study contact fatigue failure (**rivets**)

XFEM-ABAQUS

- **eXtended Finite Element Method**
- Extension of conventional FEM based on the concept of partition of unity;



XFEM-ABAQUS

$$\mathbf{u} = \sum_{I=1}^N N_I(x) [\mathbf{u}_I + H(x)\mathbf{a}_I]$$

N_I shape function

\mathbf{u}_I conventional nodal displacement

\mathbf{a}_I enriched nodal displacements

Traction-Separation Law

$$\begin{pmatrix} T_{n,0} \\ T_{t,0} \end{pmatrix} = \begin{bmatrix} K_0 & 0 \\ 0 & K_0 \end{bmatrix} \begin{pmatrix} \Delta_n \\ \Delta_t \end{pmatrix}$$

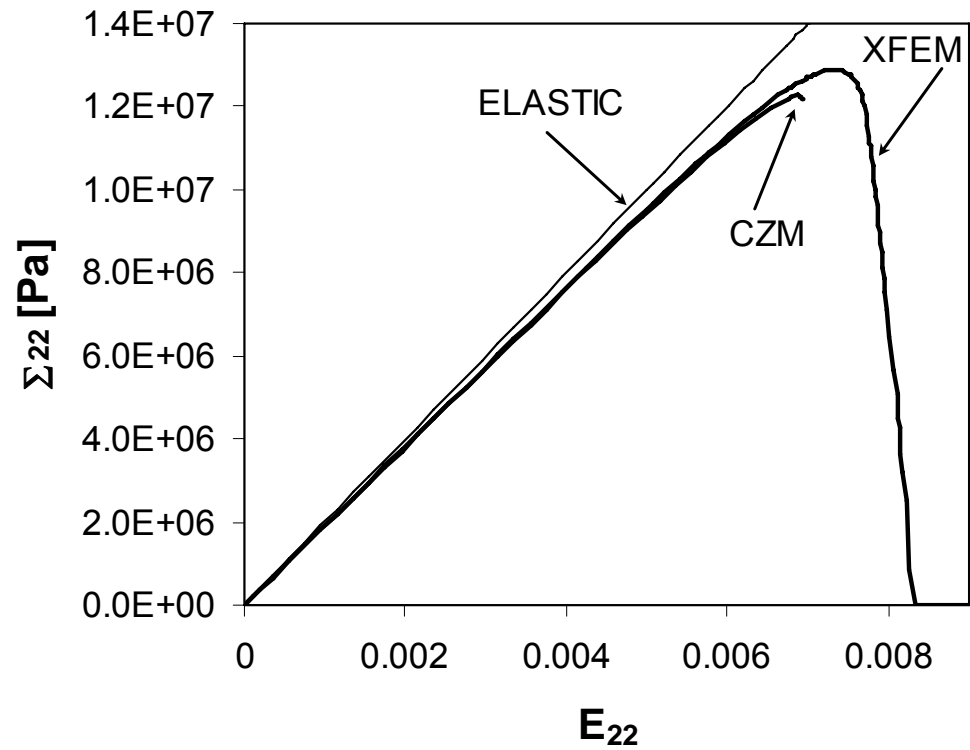
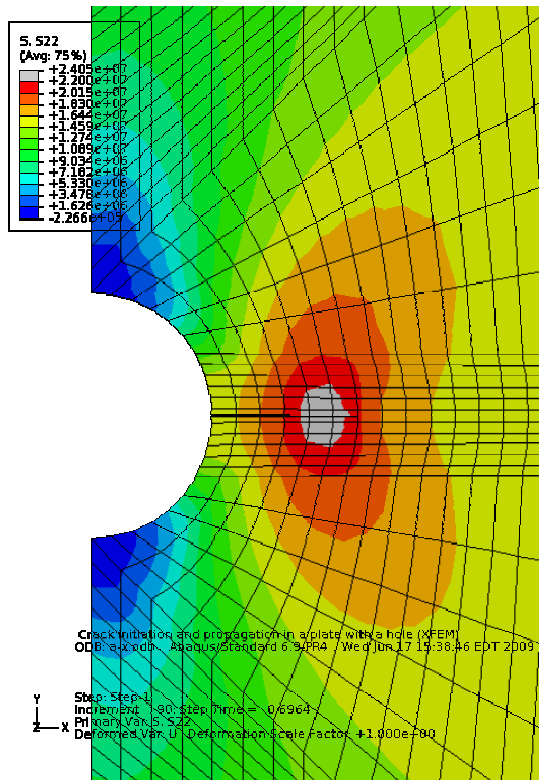
$$\max \left(\frac{\langle T_{n,0} \rangle}{\sigma_{\max,0}}, \frac{T_{t,0}}{\sigma_{\max,0}} \right) = 1$$

$$T_n = (1 - D)T_{n,0}, T_t = (1 - D)T_{t,0}$$

$$D_m = \frac{\int_0^{\Delta_m} T_{\text{eff}} d\Delta_m}{\phi_0 - \phi_{el}}$$

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Monotonic Loading



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Example: CZM vs. XFEM

- Plate with a central hole
- Remote displacements
- CZ elements along several radial lines
- XFEM enrichment throughout

Fatigue Damage Model

Cyclic damage variable: $D_C = \frac{A_{damaged}}{A_0}$

Effective tractions: $\hat{T}_n = \frac{F}{A_0(1-D_C)} = \frac{T_n}{(1-D_C)}$

Since: $\hat{T}_n = \hat{T}_n(\sigma_{max,0}, \delta_0)$

$$T_n = T_n[\sigma_{max,0}(1-D_C), \delta_0]$$

Current Cohesive Properties: $\sigma_{max} = \sigma_{max,0}(1-D_C)$,

$$\phi_n = \chi \sigma_{max} \delta_0 = \chi \sigma_{max,0}(1-D_C) \delta_0$$

Need to define : $\dot{\mathbf{D}}_C = \dot{\mathbf{D}}_C(\mathbf{D}_C, \dot{\Delta}_n, \dot{\Delta}_t, \mathbf{T}_n, \mathbf{T}_t \dots)$

Damage Accumulation Rule

- ▶ Damage accumulation starts if a deformation measure, accumulated or current, is greater than a critical magnitude.
- ▶ There exists an endurance limit which is a stress level below which cyclic loading can proceed infinitely without failure.
- ▶ The increment of damage is related to the increment of absolute value of deformation as weighted by the ratio of current load level relative to strength.

Damage Accumulation Rules

$$CZM : dD_c = \frac{|\dot{\Delta}_m|}{\delta_\Sigma} \left[\frac{T_{eff}}{\sigma_{max}} - C_f \right] , \quad D_c = \int dD_c$$

σ_fcohesive endurance limit

δ_Σcyclic cohesive length

$$XFEM : dD_c = \frac{|\dot{\epsilon}_{p1}|}{\epsilon_\Sigma} \left[\frac{\sigma_{p1}}{\sigma_{max}} - C_f \right] , \quad D_c = \int dD_c$$

σ_fcohesive endurance limit

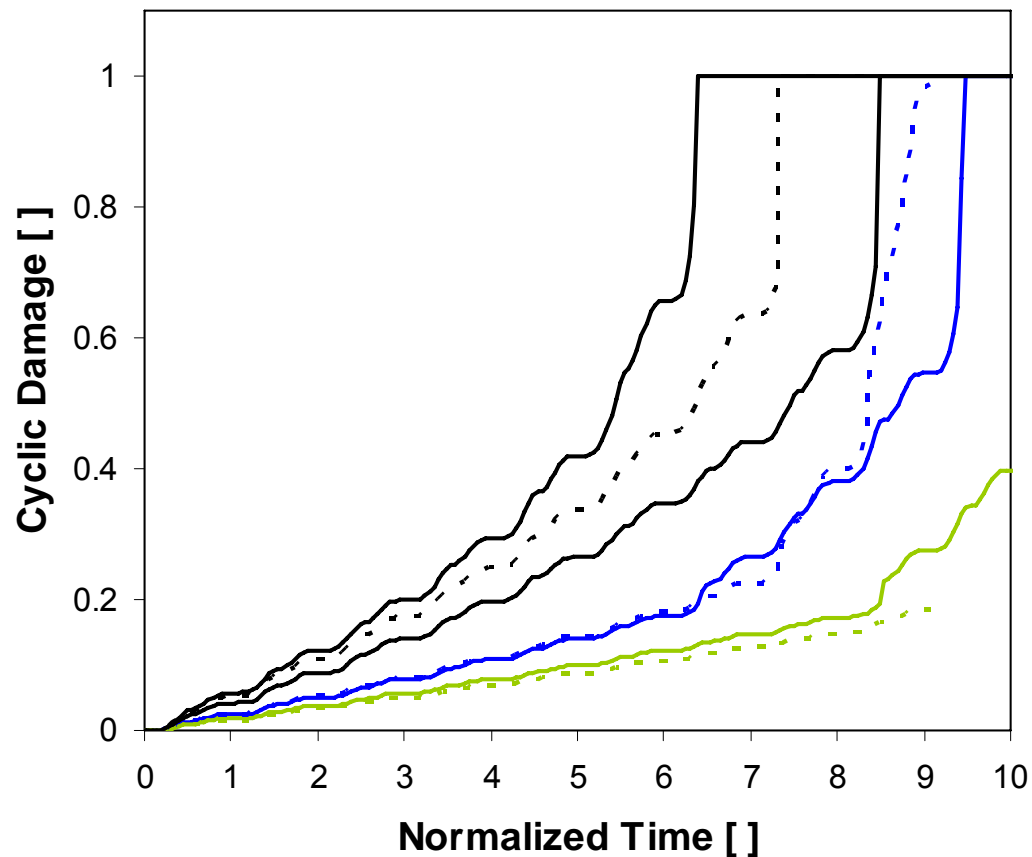
ϵ_{Σ} cyclic reference strain

$$\frac{\delta_\Sigma}{\epsilon_\Sigma} = \frac{K_0}{E_0}$$

$$\epsilon_\Sigma$$

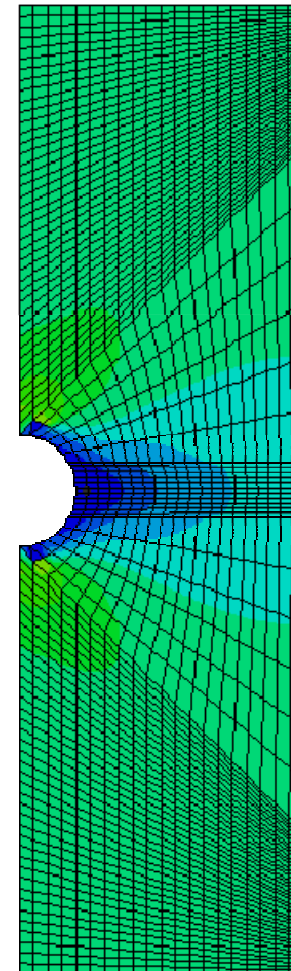
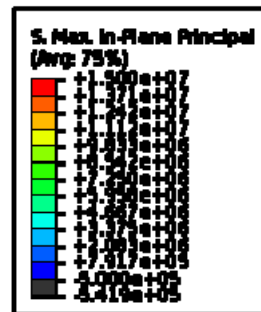
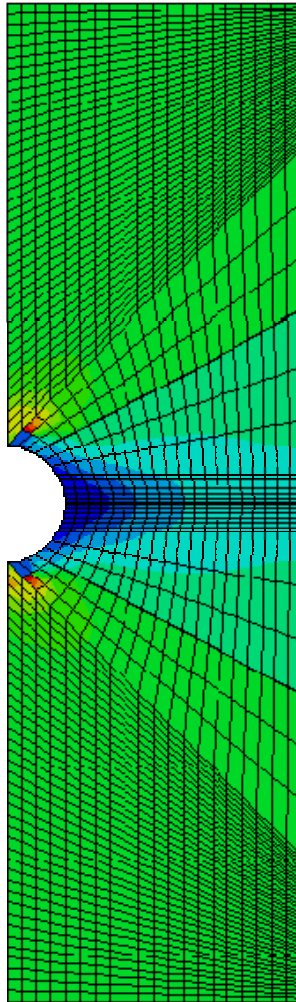
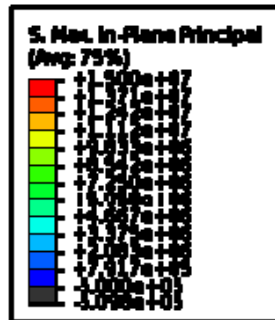
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Cyclic Loading: Damage Evolution in Mode I



the first three elements of the row of elements emerging from the hole at . -
--- 1st element CZM (both integration points shown), - -
- 1st element XFEM, ----- 2nd element CZM (lagging integration point shown), - - -
2nd element XFEM, ----- 3rd element CZM (lagging integration point shown), - - -
3rd element XFEM.

Cyclic Loading: Mixed Mode



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Contact Fatigue

- Multiaxial Fatigue Criteria:

Critical Plane Approach

E.g.: Findley Criterion:

$$\max \left\{ \tau_a + \alpha_f \sigma_{n,\max} \right\} = \beta_f$$

τ_a shear stress amplitude on a plane

$\sigma_{n,\max}$ max. normal stress on that plane

Contact Fatigue

- Multiaxial Fatigue Criteria:

Critical Plane Approach

E.g.: Findley Criterion:

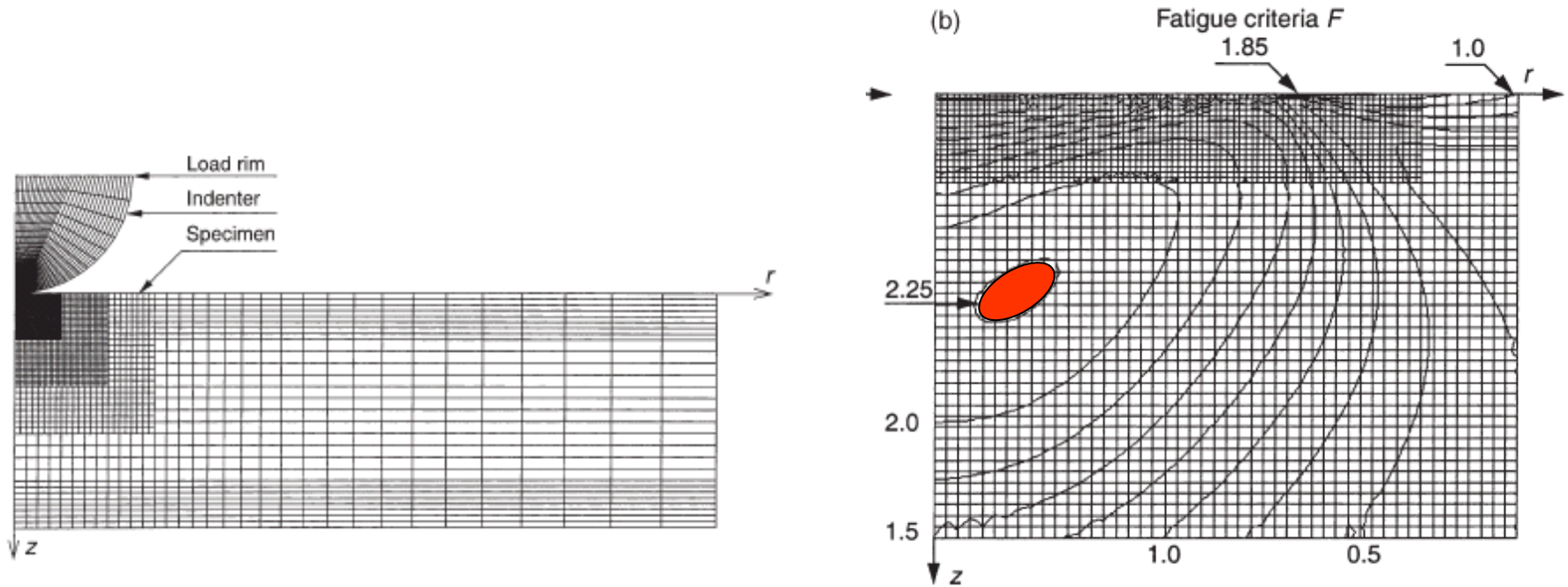
$$\max \left\{ \tau_a + \alpha_f \sigma_{n,\max} \right\} = \beta_f$$

τ_a shear stress amplitude on a plane

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Example Result

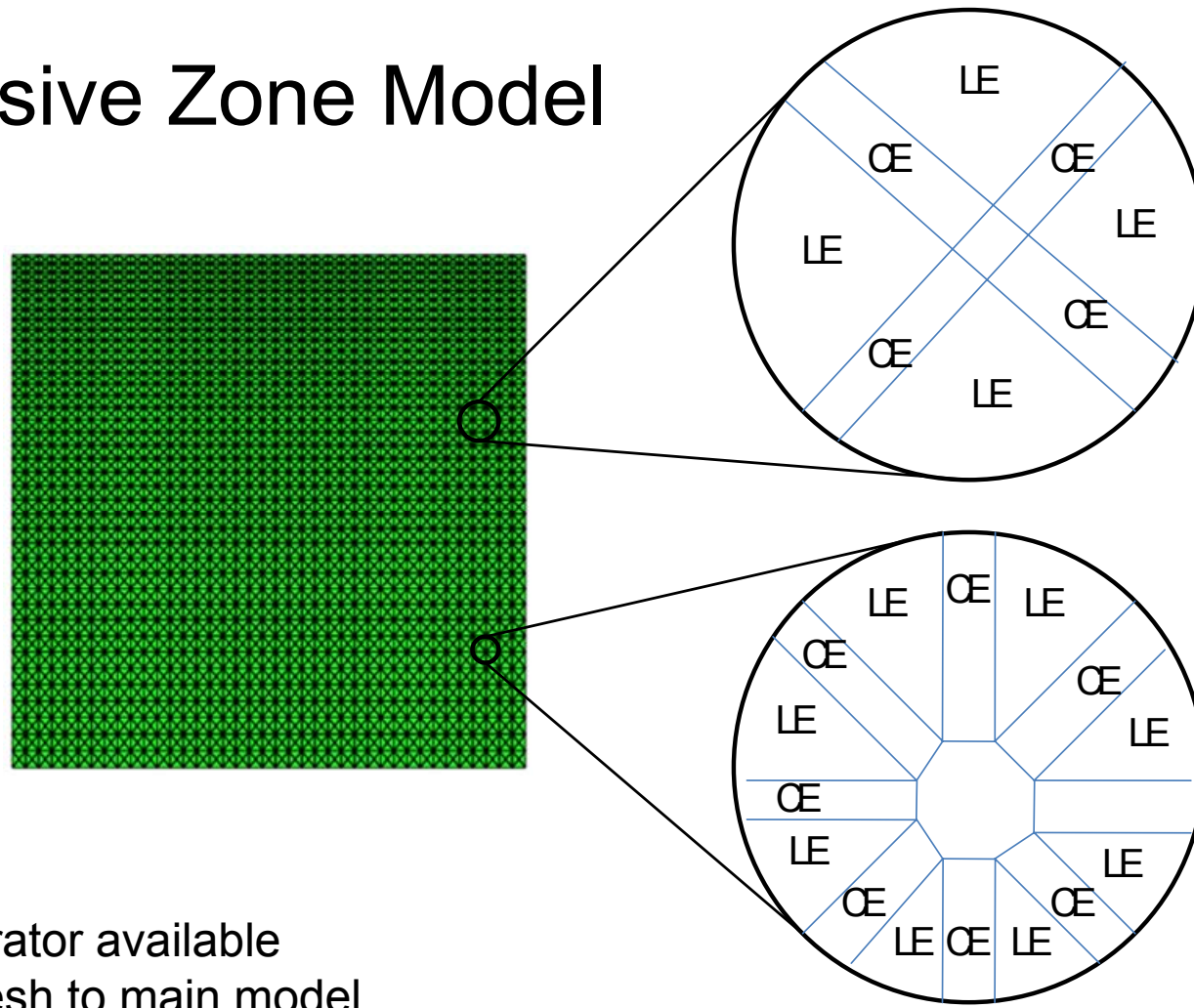
B. Alfredsson, M. Olsson / International Journal of Fatigue 23 (2001) 533–548



Provides location of crack initiation but not:
-- number of cycles to failure
-- not applicable to variable amplitude loading

CZM Approach

- Cohesive Zone Model



Mesh generator available

“Tie” CZ mesh to main model

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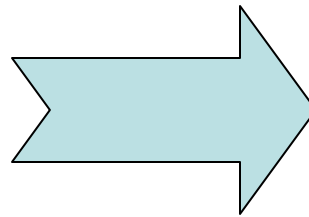
Redefine: Effective Traction

Common Fatigue Crack Growth

$$\bar{T} = \sqrt{(T_n)^2 + (T_t)^2}$$

Contact Fatigue

$$\bar{T} = \sqrt{(\eta \times T_n)^2 + (\beta \times T_t)^2}$$



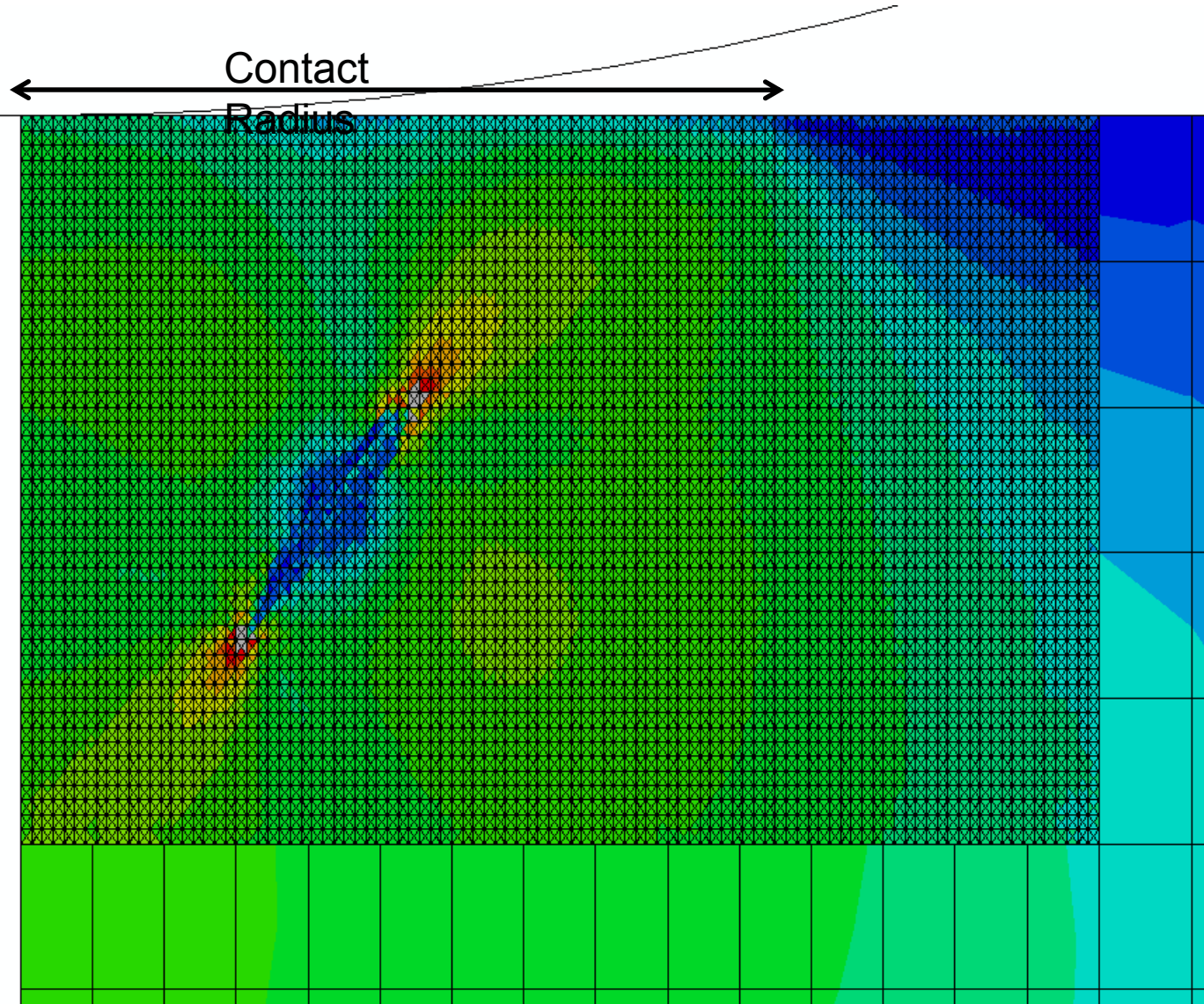
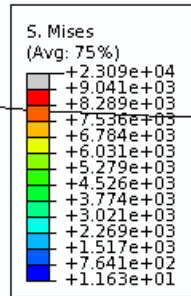
$$\bar{T} = \sqrt{\left(T_n \times \frac{0.64}{3}\right)^2 + (T_t)^2}$$

if $T_n > 0$

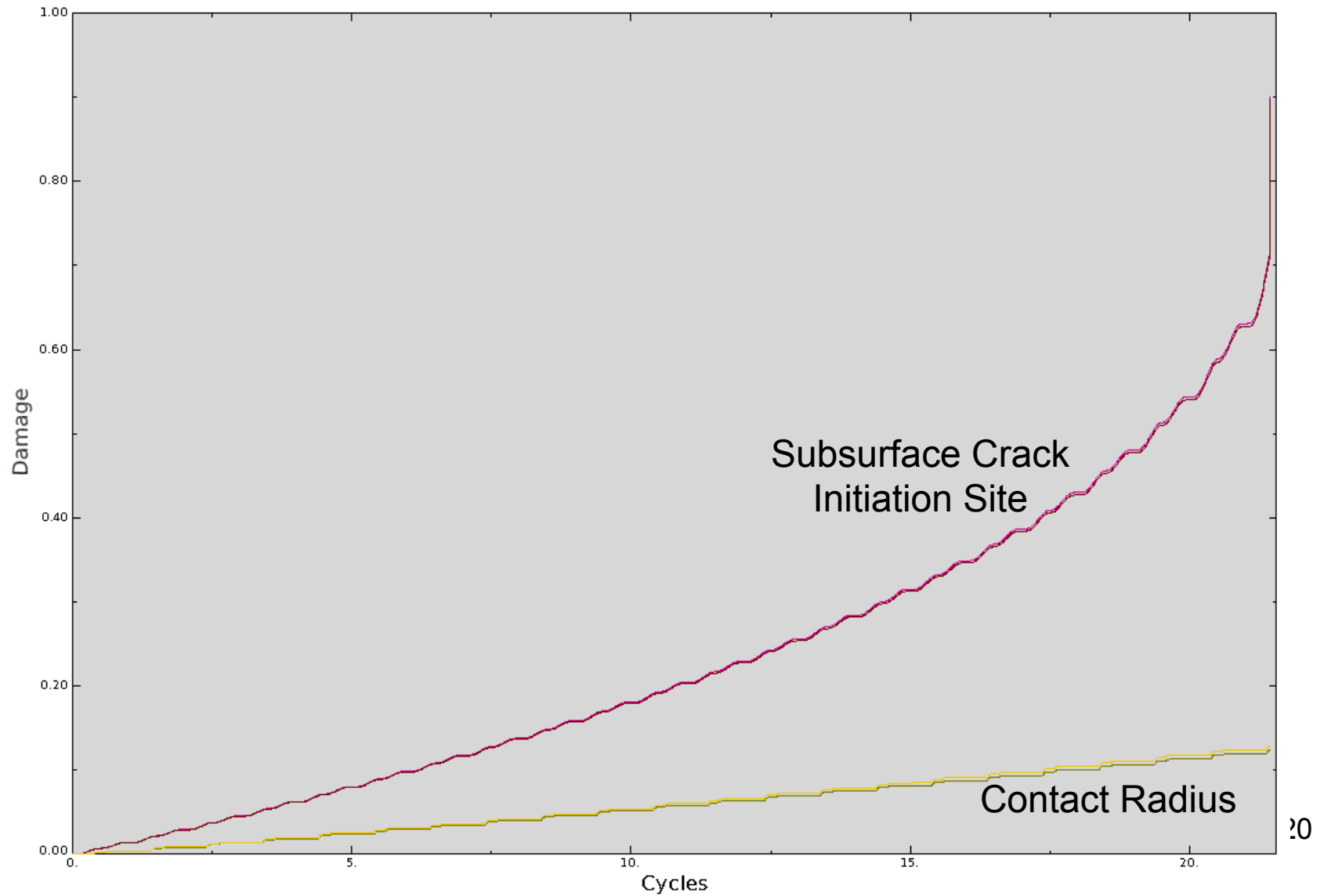
$$\bar{T} = \frac{0.64}{3} \times T_n + T_t$$

if $T_n < 0$

$P_{\max} = 16800 \text{ N at Failure}$

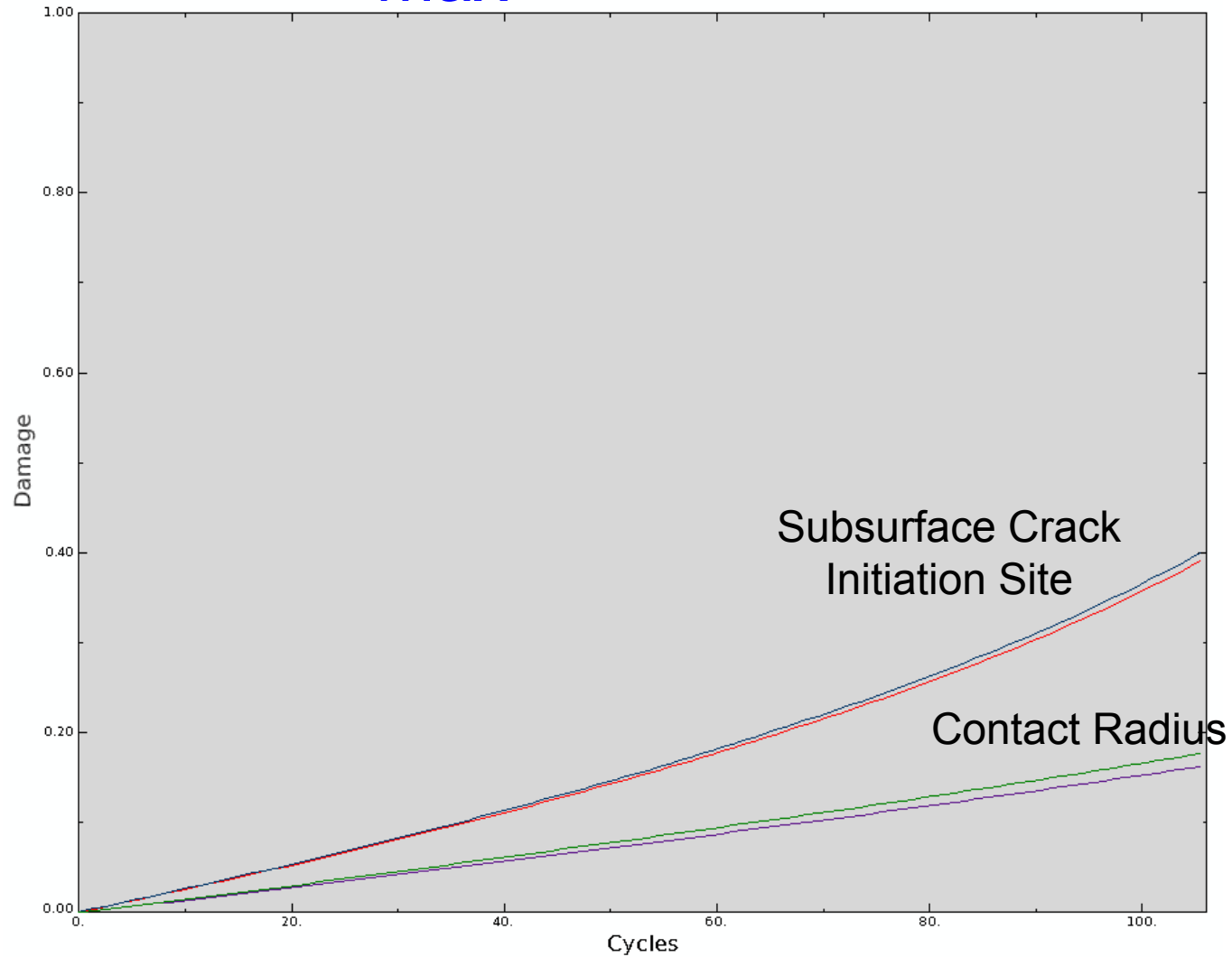


Damage Evolution

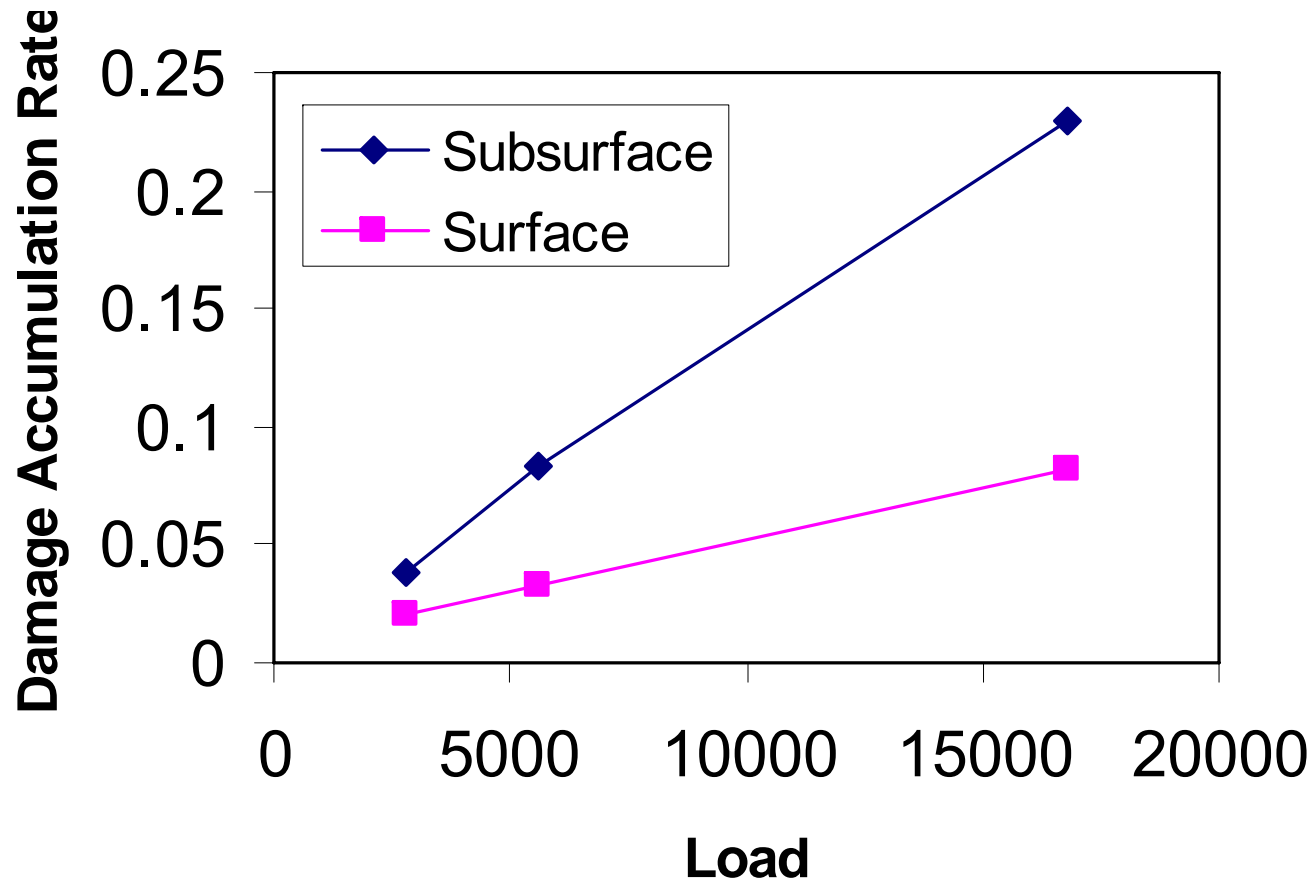


Damage Evolution

$$P_{\max} = 2800 \text{ N}$$

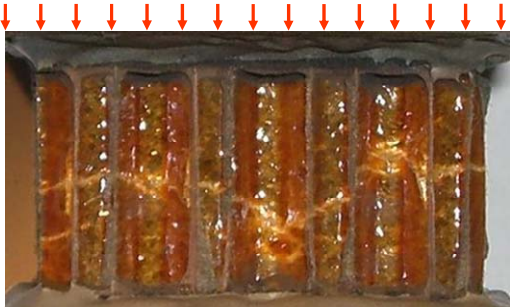


Comparison

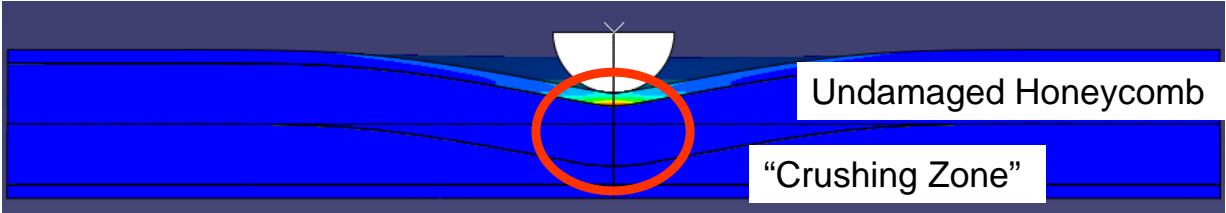
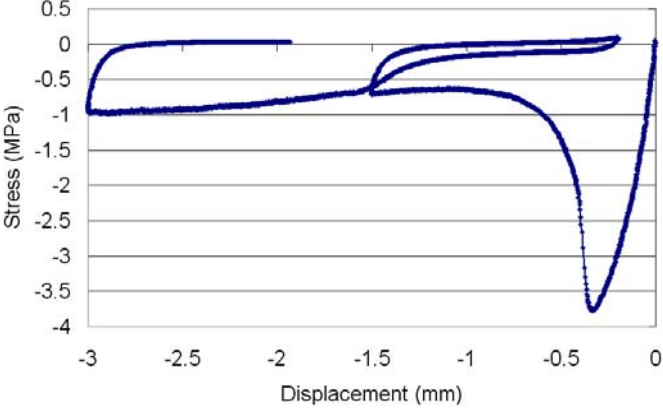
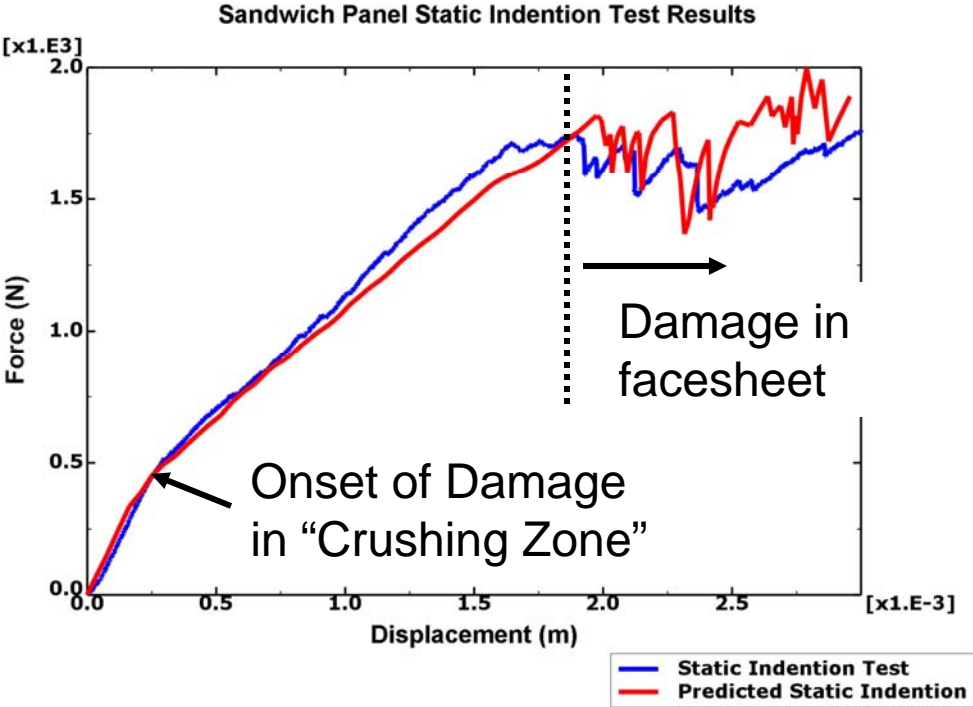


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Related Work (CACI) : Sandwich Panel Integrity



Nomex Honeycomb in a Sandwich Panel: Normal Unloading



Summary

- CZM vs. XFEM:
 - Provide close results if correctly calibrated
 - CZM is mesh dependent, XFEM less
- Contact Fatigue:
 - Multifacet CZM
 - Effective traction
 - Variable amplitude loading or tilted geometry